



Review Article

## A Review on Multidisciplinary Design Optimization of Dynamic Engineering Systems

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### Keywords

Optimization,  
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### Abstract

Dynamical system is explained as a particle movement which depend on time and predicts its future behavior. Dynamical systems are always used for some engineering problems. These problems include movements, vibrations and technology. It has several applications in automotive engineering as well. It includes the vehicle dynamic design and control systems. Although it develops the systems that helps the human life, but it also brings plenty of necessities which one of them is optimization. Multidisciplinary design optimization (MDO) should be used in the solving of dynamic engineering problems. Lacking MDO can lead to less efficiency or mismatch of system. MDO play important role in the improvement of the systems. In this article a review on the application of MDO in dynamic system is presented.

### 1. Introduction

Dynamic engineering systems have an essential role in active and autonomous dynamic systems. Multidisciplinary analysis and design techniques are also important for well-designed complex systems. When multidisciplinary design optimization is used on dynamic systems, they improve their performance. MDO in dynamic systems are significant for engineers. A phenomenal amount of work has been performed around dynamic system design. Physical system design is integral to the dynamic system design problem and must be addressed as well. Unfortunately, dynamic properties are often simplified or neglected when performing plant design. There are many solutions for these problems. Each has different mathematical representation [1].

Engineering design is the process of devising a system, component, or process to meet desired needs. It is a decision-making process (often iterative), in which the basic sciences, mathematics, and the engineering sciences are applied to convert resources optimally to meet the stated [2]. System is a complete thing which has a goal. It includes units that are depending and affecting each other. Also, it has certain plans [3]. Multidisciplinary design's the engineering design of systems that have at least two interdependent disciplines. It

obtains that performance of one discipline which is influenced by design requirements in other disciplines and decide the design with using this performance data [1]. Multidisciplinary Design Optimization (MDO) is engineering process that uses optimization methods to make optimal design between related disciplines [4].

### 2. Lecture Review

In 1970, S. De Julio in [5] studied on new technique about approximate computation of optimal controls. This technique can be applied particular linear systems which is governed by partial differential equations when the cost functionals are quadratic. The technique tried on both systems with distributed and boundary control. The results are consistent for both. It seems if we accept to obtain weak convergence of the optimal solution. the technique looks practical [5].

Controllability and observability criteria are important parameters for linear dynamical systems. These parameters don't affect the systems directly, but they give the information about measuring of the quality. There are three physical measures which are about the qualities of controllability and observability of dynamical systems. For

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example, there are some works in satellite attitude control problems [6].

In 1978, problem of Titli and Singh was priority, because they didn't have enough equipment and there were two optimization problems which can solve with multi-processor system with hierarchical structure. First case is distributed parameter system and second case is traffic control problem. They tried to which one can be [7].

In 1980, Large scale systems were problem to solved and required more calculation power. They tried new method which was iterative to obtain some information about optimization of large scale systems [8].

In another work BY Manon et al. [9], a class of hybrid dynamical system. These systems operate in multiple phases. There are two different methods to minimize the operating time during process. First method contains of criterion minimization with respect to constraints. Second method contains of Pontragin's maximum principle. For example, Improving the design data and properties of wind turbines, scaling trends such as loading, mass, and cost etc. [10].

In the other work by Laudini et al., [11] the swarm/flock optimization algorithms is used in continuous dynamic systems, generally, optimization algorithms originated to classic swarm intelligence. Numerical swarm/flack-based algorithms turn to differential equations in time domain and closed-forms. Thanks to using circulant matrices for the representation of connection between molecules by via of time approach. The benefit of this integration that it provides functions of time, and these can be update the position and the velocity of each particle in time window. For instance, the leader agent manages topology of the network in its neighbourhood and increases flocking velocity [12].

Particle swarm optimization (PSO) is also using dynamic economic dispatch of power systems. The optimization model of this system is required to obtain some variables about the systems which is power system to improve. This paper's aim is how PSO effected power systems' optimization [13].

Different work by Jung and Park [14] indicates that optimization methods aim to improve design of structural and control systems. If there are more than two systems which may be including structural and control system. The integrated systems should examine together and all of them try to get better performance. Example of this system, which is generally in mechatronic field, the multidisciplinary optimization method is applied to the design of mechatronic vehicles with active suspensions [15].

In another work by Adami et al. [16], several examples were presented. For the optimizing of these systems, structural analysis, heat transfer, aerodynamics and control were done. In the practice of this system [17], paper explained the methodology of optimization of these systems. Also, it explains how to get better performance.

In this paper, there are several starting priors of solution that are useful for estimate the initial points. Methods include warm start from a prior solution, linearization, structural decomposition, and an incremental unbounding of decision variables that leads up to solving the originally intended problem. Several optimization problems are expanding some

topics which are many benchmark tests, energy storage, aerial vehicle etc. [18].

In the paper from [19], the multi-functional optimization algorithm is used for dynamical systems. The problem is defined for control problem which is updated by using the gradient estimation. In Pareto Optimality, there are some inputs which is developed along to Pareto descent direction. This is succeeded by solving the linear programming problem. As an example, development of air foils shows these properties [20].

Also, there are some practice in topology optimization. One of them is in the motion systems which aim to better accuracy, higher speed and larger scale and high-performance design. The goal of topology optimization is that decide the best material quantity and quality with a design volume [21]. This approach is significant for aerodynamic design issues. There are some parameters are about limitations of system. Physical behavior is explored using a case study for aero-structural optimization along with other physical quantities and quality with established behavior [22].

Cities population is also dynamical system, so they have some problems which may solve. When solving these problems, optimization methods can be useful. This work explained mathematical model of cities and solve this function using optimization models. Results show that this approach is useful for people dynamics [23].

Ordinary differential equation systems use to find optimal solutions of the dynamical system problems. Especially, they use for low dimensional problems and for larger system which is unable to estimate bounds. In the paper, interval contractors are used for bounded optima. Upper and lower bounds on the dynamic parameters using on objective function is related to first order sensitivity equation. The method solves the tight limits [24].

The air and water exchanges are limited in recirculation aquaculture system (RAS),so the facility ventilation is crucial component for the preventing toxicity. The facility ventilation systems consume elevated energy and this paper deals with decreasing that energy consuming by dynamic facility ventilation [25].

There are challenges for optimization in dynamic environments. In a work by Ye et al. [26] suggested a novel multi-swarm particle swarm optimization with dynamic learning strategy to improve the performance of PSO in 2017. Among all sub-swarms, each sub-swarm must be classified into ordinary particles and communication particle with separated task for each iteration due to provide information exchange between subswarms. There two types of particles; ordinary particles and communication particles. The method leans on setting dynamic control mechanism with an increasing parameter "p" for implementing the classification operation provides ordinary particles an increasing sense of evolution into communication particles during the searching process.

The study of Lorenz T. Biegler on advanced optimization strategies for integrated dynamic process operations in 2017 discusses the effectiveness of dynamic optimization on three case studies on real-world chemical processes This study discusses and demonstrates the effectiveness of dynamic

optimization on three case studies on real-world chemical processes. In the first case, we consider the optimal design of runaway reactors, where simulation models may lead to unbounded profiles for many choices of design and operating conditions. As a result, optimization based on repeated simulations typically fails, and a simultaneous, equation-based approach must be applied. Second, we consider optimal operating policies for grade transitions in polymer processes. Modelled as an optimal control problem, we demonstrate how incorporation of product specification bands leads to multistage formulations that greatly improve process performance and significantly reduce off-grade product. Third, we consider an optimization strategy for the integration of scheduling and dynamic process operation for general continuous/batch processes. The method introduces a discrete time formulation for simultaneous optimization of scheduling and operating decisions. Finally, we provide a concise summary of directions and challenges for future extension of these optimization formulations and solution strategies [27].

Concepts of electrical vehicles include hybrid batteries. This study concerned utilization, dimensioning and operation of hybrid battery systems. Main purpose of this paper is elaborate the energy optimization on hybrid battery system. Two optimization methods are used for given system and control problem. by working on stochastic modelling, control laws obtained and that laws applied given system which include vehicle drivetrain and vehicle chassis. After that performance of controllers are compared [28].

The fundamental mechanical engineering challenge of mechanism design is the subject which this paper deals with. Since there are few, if any, approaches that consider kinematic synthesis and optimization of dynamic performance in an integrated manner, while there is a significant body of research associated with mechanism design. To address this gap, this paper presents a multi-level, also called layered, design optimization approach that enables kinematic and dynamic optimization combined with velocity profiling of the motor/drive system. The approach is presented for both new design and redesign tasks, and is based on the use of inverse kinematic and inverse dynamic analysis, and a novel strategy for generating instantiations of spatial mechanisms that satisfy kinematic quality indicators but with improved dynamic performance. The experimental results validate not only the separated stages of the approach and the models but the overall improvements achievable through the application of the method as well. In this regard, the experimental mechanism which is also called practical, exhibited performance improvements in the peak-to-peak torque of 63%, which correlate closely with those calculated theoretically after kinematic and dynamic optimization. The introduction of a velocity cam function is shown for improving the dynamic quality indicators further and an overall reduction in peak-to-peak torque demand of 85% is resulted 29.

The matter of the paper based on adapting the particle swarm optimization (PSO) to the dynamic economic emission dispatch (DEED) problem. The paper focuses on to evaluate the performance of different variants of the PSO with Avoidance of Worst Locations (PSO AWL) against the variants of the standard particle swarm optimization (SPSO).

The results showed that the compatibility of the PSO to the DEED problem [30].

In a series of publications by Ranjbar et al. [31-58], the concept of multidisciplinary engineering design optimization of various dynamical systems in cars were investigated and reported. They showed the effect of optimization in the improvement of the quality of results.

### 3. Conclusions

Optimization problems are created for improving the systems. We examined the dynamical systems and related topics in many fields. Also, optimization methods are compatible, so we can obtain objective function in every fields. We can solve these function with lots of technics and methods. These optimization methods are useful for improving efficiency and reducing cost of systems. We discuss some of technics and methods about multidisciplinary design optimization. These technics generally include mathematical colorations and experiments results. We try to solve these colorations and we want to obtain exact values, but we cannot always reach exact values and then we try to reach the near values. For these values, we can also investigate experimental results. During, approach the result, system can reach the optimized conditions. These papers' goalis optimizing the systems. Each paper has different way to solve the functions of the optimization problems. Some papers focus on for example time and cost. The others concentrate another parameter. The result of optimizing process advise the further improvements. As a direction for future study, we will deal with some methods such as but not limited to [59-76].

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